

Virtual Robot

AI and Robotics,
Teach your robot
how to move.



Search or type a command



- Activity
- Chat
- Teams
- Calendar
- Calls
- Files
- ...



Waiting for others to join...

00:06 [Mute] [Microphone] [Screen Share] [More] [Hand] [Chat] [Participants] [End Call]

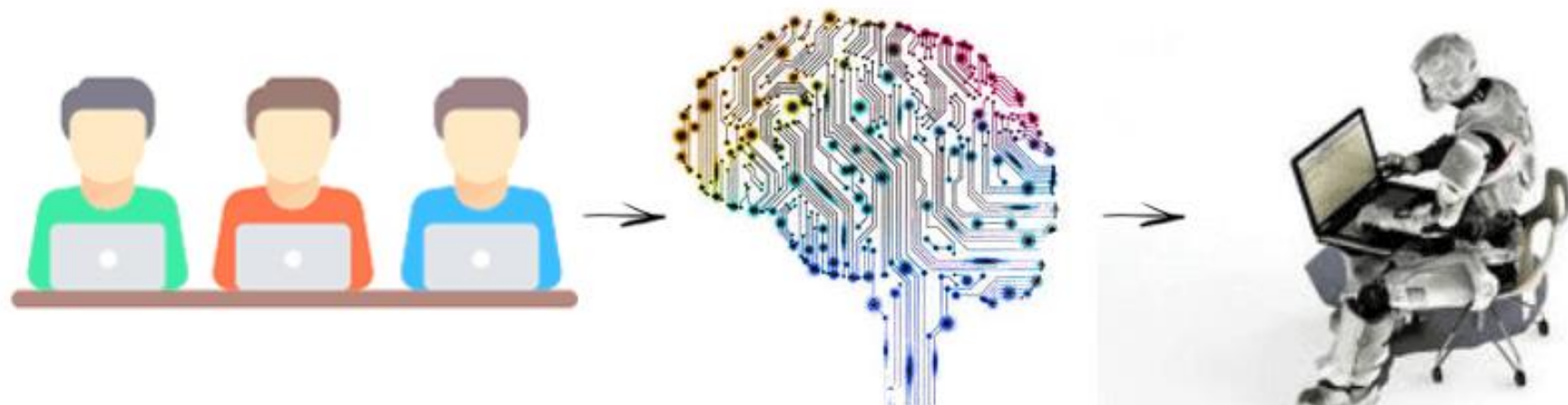
AI IS (Artificial Intelligence)

A system's ability to correctly interpret external data, to learn from such data, and to use those learnings to achieve specific goals and tasks through flexible adaptation.



Why We Need AI..??

We are growing at huge rate, say it in terms of population, scripted knowledge, tasks etc. Increasing in scale also increase entropy in system, demanding huge number of tasks to be automated, and centralized.



Why do we need Artificial Intelligence?

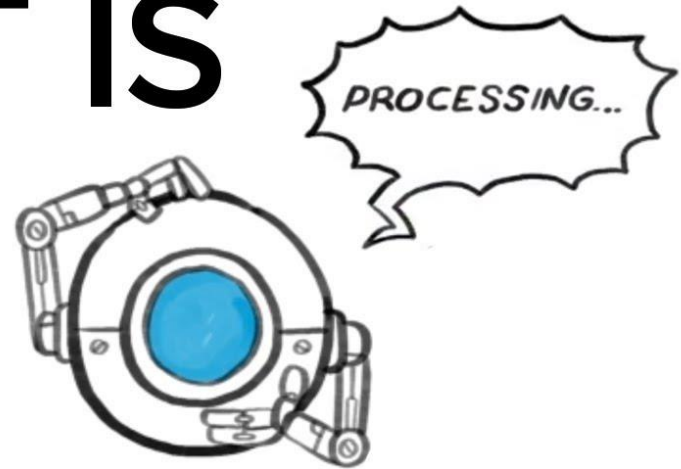




How AI works

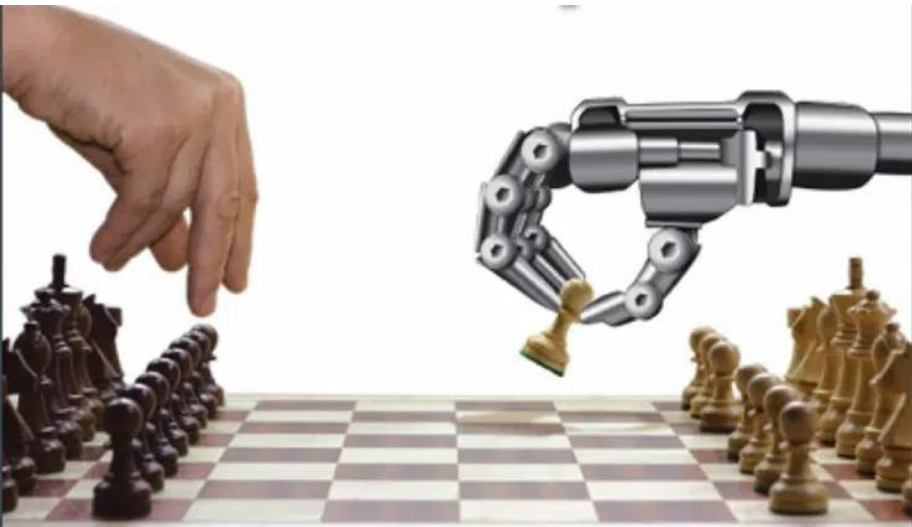
AI works by combining large amounts of data with fast, iterative processing and intelligent algorithms, allowing the software and machines to learn automatically from patterns or features in the data.

WHAT IS AI?



Types and stages of AI

REACTIVE MACHINES

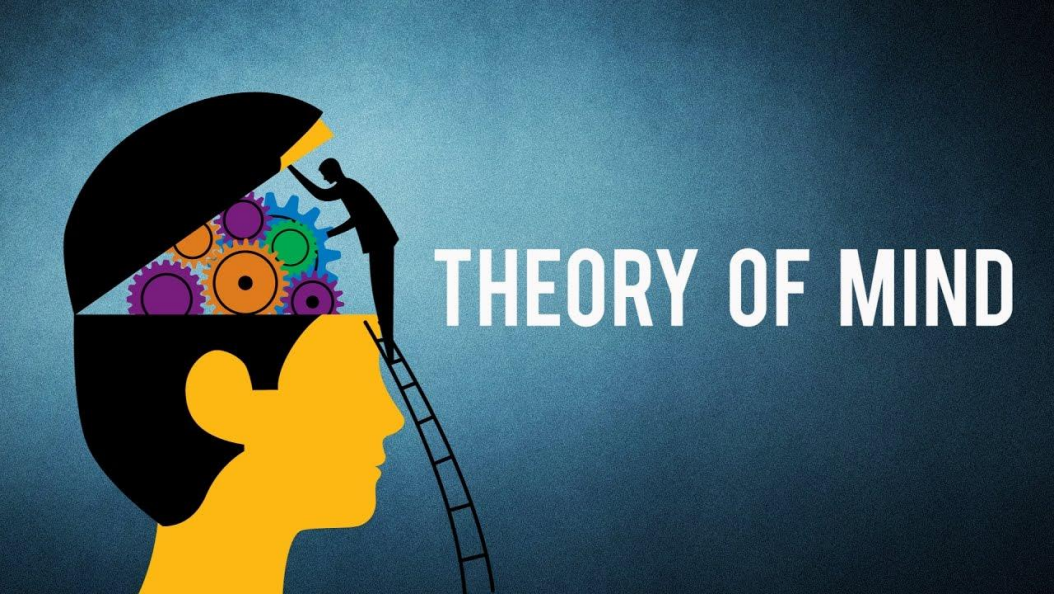


LIMITED MEMORY

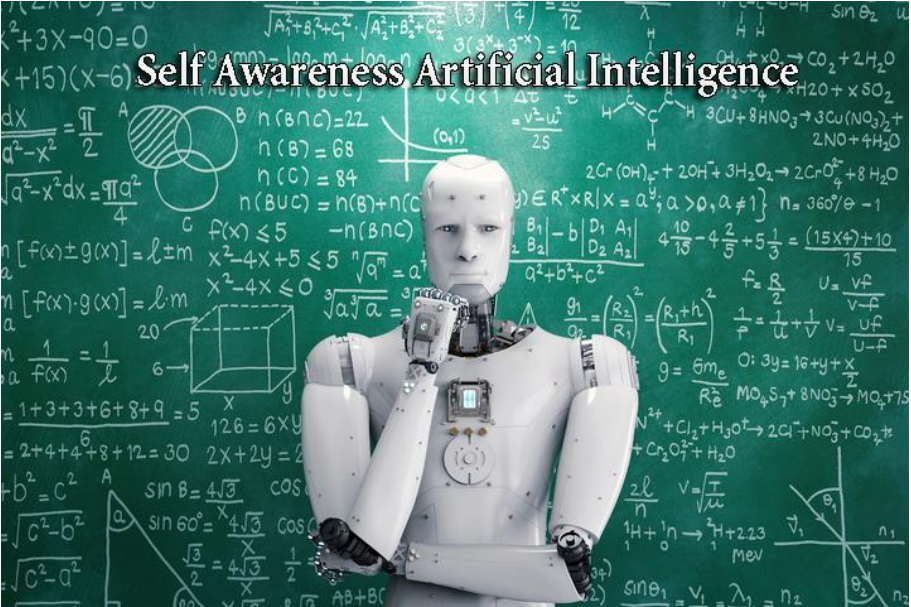


Types or stages of AI

THEORY OF MIND



SELF-AWARENESS



Robots

Robot is a machine—especially one programmable by a computer— capable of carrying out a complex series of actions automatically.



WHY DO WE NEED ROBOT??

Factory



AT HOME



AT WORK

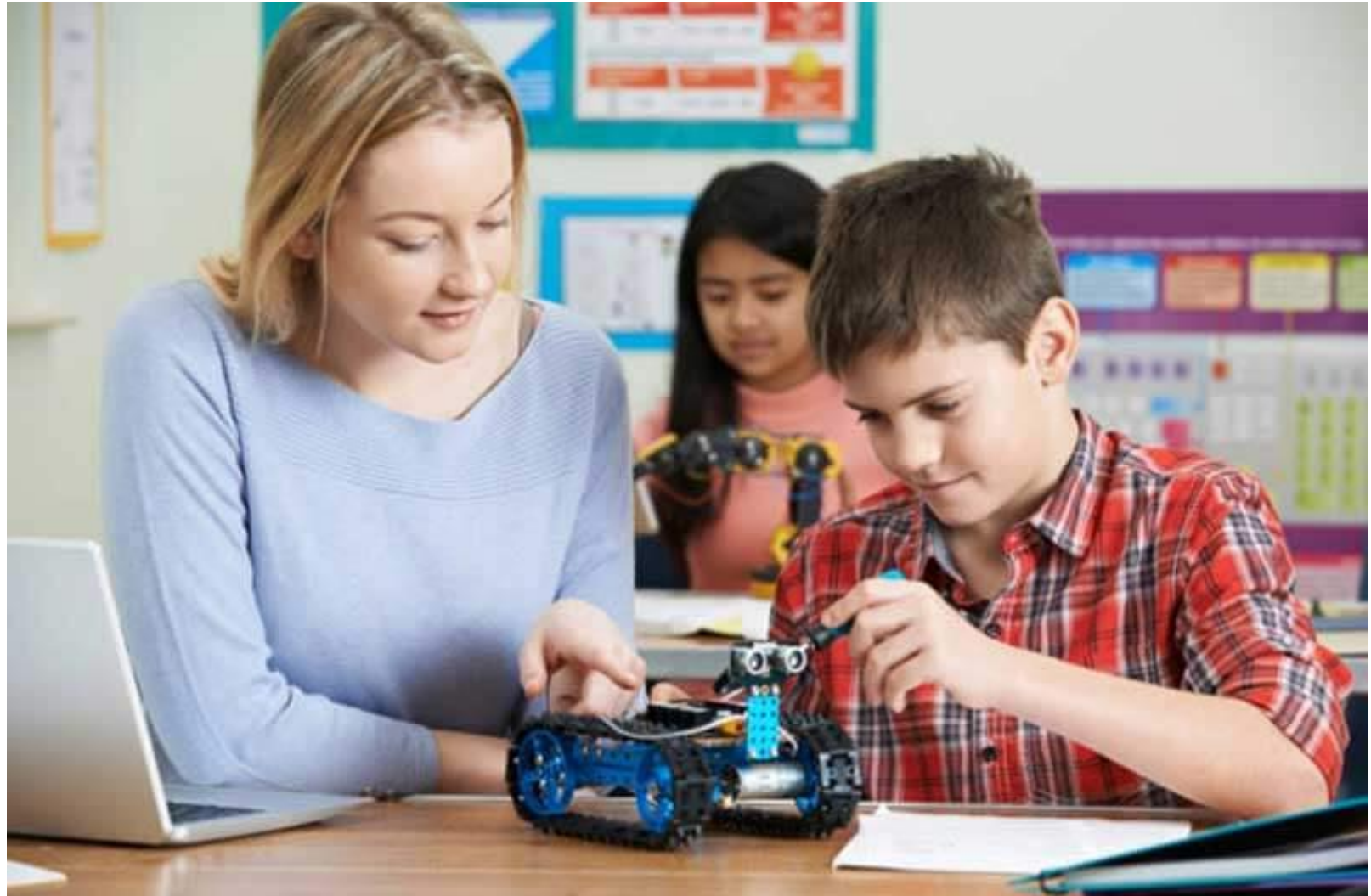


IN SPACE

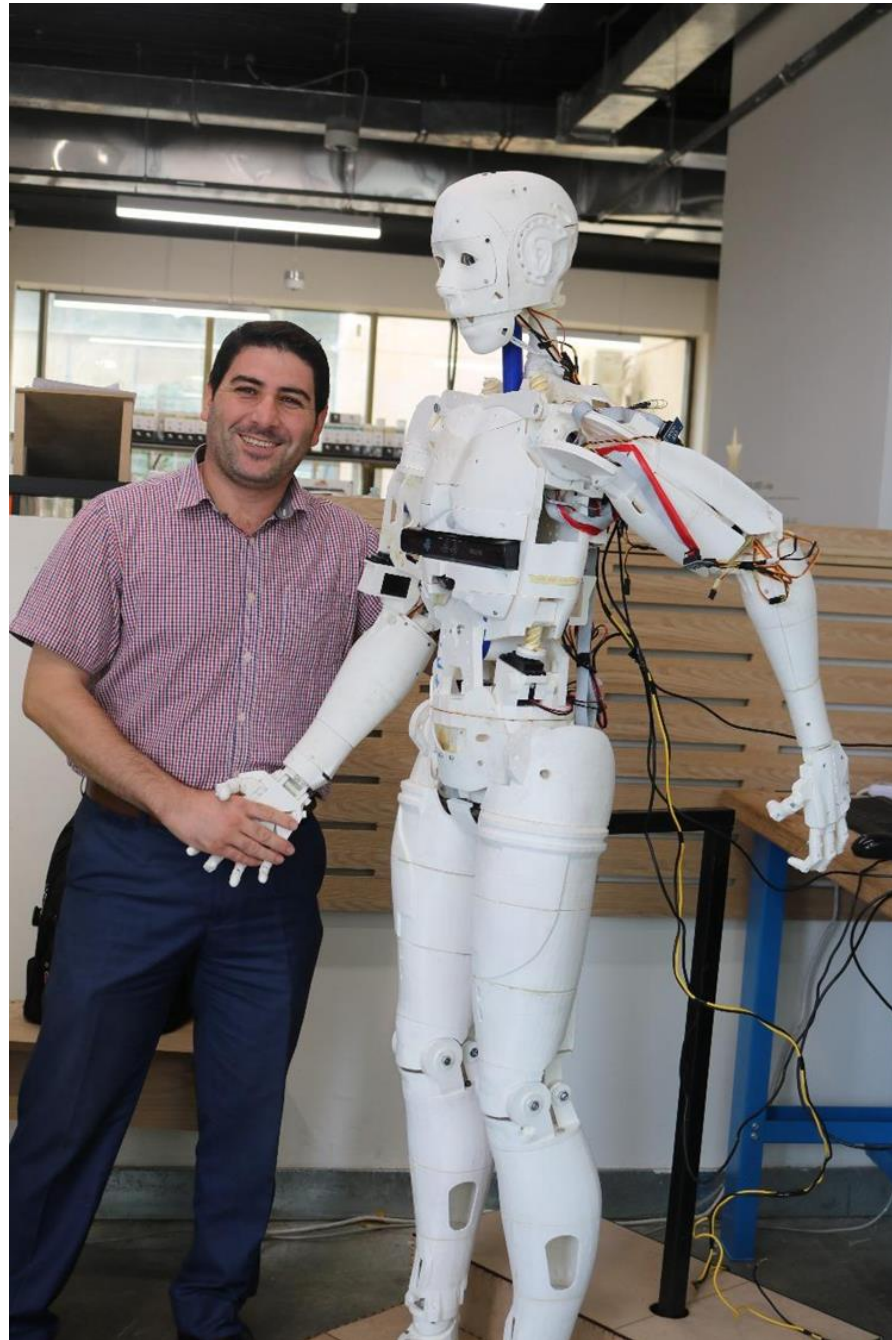




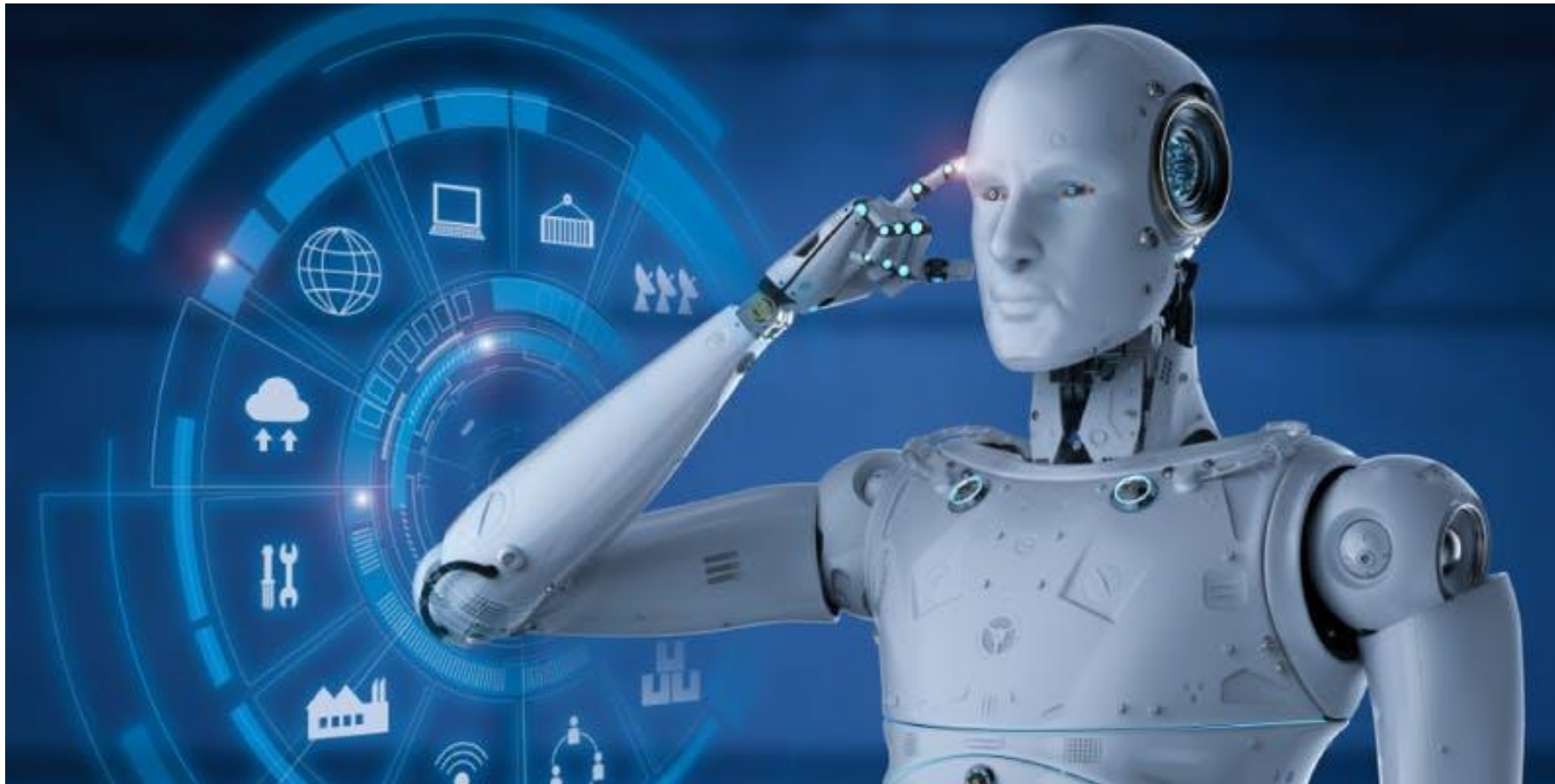
IN EDUCATION



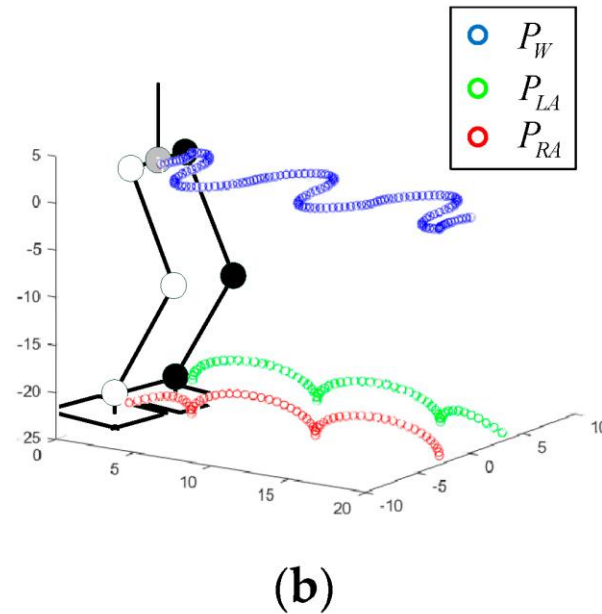
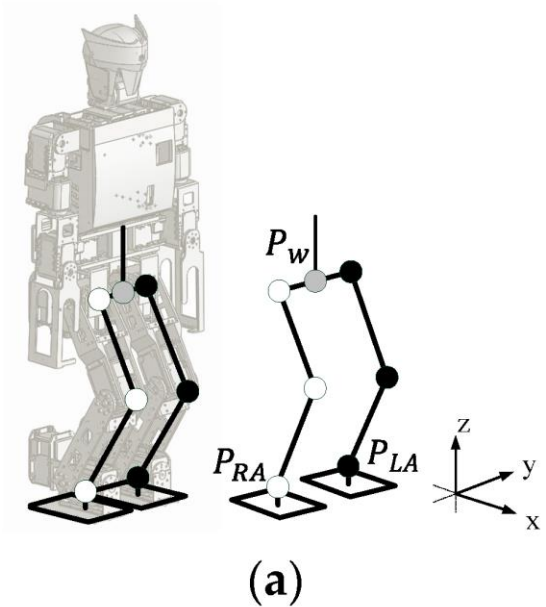
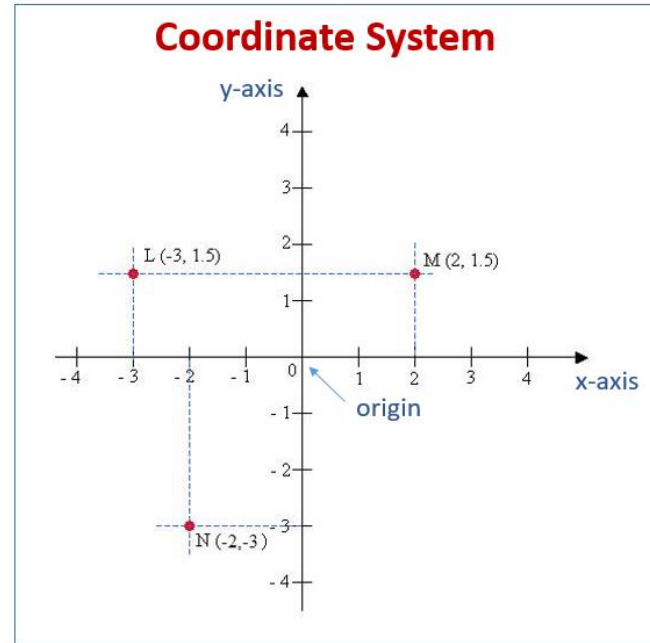
AS A FRIEND



Robots and AI



How to Teach Your Robot to Move (Coordinate System)



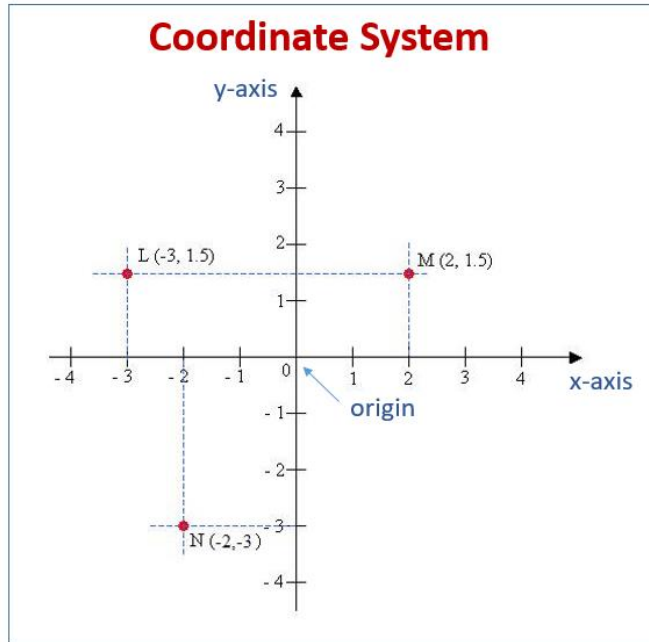
AI dangerous???

Will robots take over the world???



Today

Coordinate System



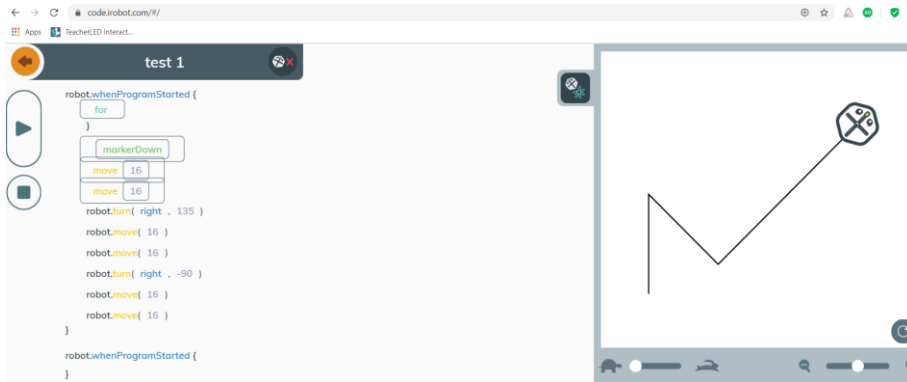
Teach the Robot with Block Coding how to move in a specific way.

The screenshot shows the code.robots.com web interface. The workspace contains a sequence of blocks for a robot program:

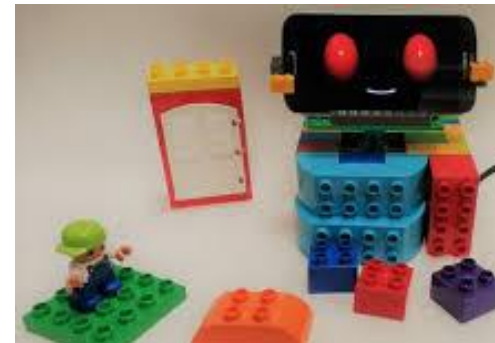
- when green flag clicked
- set motor power to 100%
- move 100 units
- turn 90 degrees
- move 100 units
- turn 90 degrees
- move 100 units
- turn 90 degrees
- move 100 units
- turn 90 degrees
- move 100 units

The workspace also shows a drawing of a robot's path forming a zig-zag shape.

Later



```
robot.whenProgramStarted (  
  for (  
    markerDown  
    move 16  
    move 16  
    robot.turn( right , 135 )  
    robot.move( 16 )  
    robot.move( 16 )  
    robot.turn( right , -90 )  
    robot.move( 16 )  
    robot.move( 16 )  
  )  
)  
robot.whenProgramStarted (  
)
```



THANKS



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